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## SCR algorithm: saving/restoring states of file systems

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**Source** [ACM SIGOPS Operating Systems Review](#) [archive](#)

 Volume 33 , Issue 1 (January 1999) [table of contents](#)

Pages: 26 - 33

Year of Publication: 1999

ISSN:0163-5980

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**Publisher** [ACM Press](#) [New York, NY, USA](#)
**Additional Information:** [abstract](#) [index terms](#) [collaborative colleagues](#) [peer to peer](#)

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### ↑ ABSTRACT

Fault-tolerance is very important in cluster computing. Many famous cluster-computing systems have implemented fault-tolerance by using checkpoint/restart mechanism. But existent checkpointing algorithms can not restore the states of a file system when roll-backing the running of a program, so there are many restrictions on file accesses in existent fault-tolerance systems. SCR algorithm, an algorithm based on atomic operation and consistent schedule, which can restore the states of file systems, is present in this paper. In SCR algorithm, system calls on file systems are classified into idempotent operations and non-idempotent operations. A non-idempotent operation modifies a file system's states, and an idempotent operation does not. SCR algorithm dynamically follows the tracks of a program's running, logs each non-idempotent operation used by the program and the information that can restore the operation in disks. When checkpointing roll-backing the program, SCR algorithm will revert the file system states to the last checkpoint time. By using SCR algorithm, users are allowed to use any file operation in their programs.

### ↑ INDEX TERMS

#### Primary Classification:

D. Software



D.4 OPERATING SYSTEMS



D.4.5 Reliability


**Subjects:** [Fault-tolerance](#)

#### Additional Classification:

D. Software



D.4 OPERATING SYSTEMS



D.4.5 Reliability

↳ **Subjects:** [Checkpoint/restart](#)

**G.** [Mathematics of Computing](#)

↳ **G.4** [MATHEMATICAL SOFTWARE](#)

↳ **Subjects:** [Algorithm design and analysis](#)

### General Terms:

[Algorithms](#), [Design](#), [Performance](#), [Reliability](#), [Theory](#), [Verification](#)

### Keywords:

[atomic operation](#), [checkpointing](#), [fault-tolerance](#), [recoverability of file systems](#)

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# SCR ALGORITHM: SAVING/RESTORING STATES OF FILE SYSTEMS

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**Abstract** Fault-tolerance is very important in cluster computing. Many famous cluster-computing systems have implemented fault-tolerance by using checkpoint/restart mechanism. But existent checkpointing algorithms can not restore the states of a file system when roll-backing the running of a program, so there are many restrictions on file accesses in existent fault-tolerance systems. SCR algorithm, an algorithm based on atomic operation and consistent schedule, which can restore the states of file systems, is present in this paper. In SCR algorithm, system calls on file systems are classified into idempotent operations and non-idempotent operations. A non-idempotent operation modifies a file system's states, and an idempotent operation does not. SCR algorithm dynamically follows the tracks of a program's running, logs each non-idempotent operation used by the program and the information that can restore the operation in disks. When checkpointing roll-backing the program, SCR algorithm will revert the file system states to the last checkpoint time. By using SCR algorithm, users are allowed to use any file operation in their programs.

**Key Words:** fault-tolerance, checkpointing, atomic operation, recoverability of file systems.

## 1 Introduction

Cluster computing systems, such as PVM<sup>[1]</sup>, have been more and more important parallel computing environments due to their good performance/cost and large computing ability. However, the more machines are involved in a computing, the fault rate is higher. Hence, improving the reliability of cluster computing systems is necessary. To provide a reliable computing environment to users, many cluster computing systems realized fault-tolerance by using checkpointing algorithms, such as Condor<sup>[2,3]</sup>, Mist<sup>[4,5]</sup>, CoCheck<sup>[6]</sup>, Fail-safe PVM<sup>[7]</sup>, and Dome<sup>[8,9]</sup> etc.

A computing is composed of data and program. Checkpointing is usually used to improve the program's reliability. Periodically, checkpointing algorithms take global checkpoint to save the current running states of a program in the stable storage. When a failure occurs, checkpointing algorithms roll-back the program to the last checkpoint cut to mask the failure.

Data are usually saved in files. Usually, two methods are used to improve the availability of a distributed file system<sup>[10]</sup>. One is to make file systems recoverable, the other is to make file systems robust. A file is recoverable if it is possible to revert it to an earlier, consistent state when an operation on the file fails or is aborted by the client. Recoverable files are realized by atomic updated techniques, and mainly used in data base systems. A file is called robust if it is guaranteed to survive crashes of storage device and decays of the storage medium. Robust files are implemented by redundancy techniques such as mirrored file and RAID<sup>[11-14]</sup> etc.

In cluster computing systems it is necessary to realize recoverability of file systems for supporting fault-tolerance. File systems are very important environments for programs. During running, a program needs access file systems for reading input or writing output from time to time. So incorrect file system states will lead to program's error running. Existing fault-tolerance systems only rollback a program's running states and dose not restore the file system states correspondingly. If the program executed the operations that modified the file system states, such as delete, rename, ..., the program would rerun in a changed file system environments. Then the program's running is unpredictable. For this reason, Condor, Mist and other fault-tolerance systems disallow their users to access file systems arbitrarily except read-only or write-only operations. Such restrictions prevent general applications from using checkpointing to improve reliability. In [15], random write and read are considered as unrecoverable operations. [4] thinks that write-and-copy technology may be used to resolve the problem, but no further work is reported.

In the paper, SCR algorithm, which is based on atomic operation and consistent schedule, is presented. SCR algorithm develops the concept of file systems recoverability in that it can revert a file system's states

changed by a program's running, not only by a single file operation. By using SCR algorithm, synchronous checkpointing algorithms<sup>[16]</sup> may allow arbitrary file accesses in user applications.

The rest of the paper is organized as the following: Section 2 gives out the important concepts and definitions. SCR algorithm and its proof of correctness are given in section 3. In section 4, an implementation example of SCR algorithm is presented. Section 5 discusses SCR algorithm's performance, and the last section concludes the paper.

## 2 Concepts and Definitions

Two general strategies can be used to realize saving/restoring the states of a distributed file system corresponding to a distributed program's fault-tolerance running. One is static save/restore strategy (SSR), the other is dynamic save/restore strategy (DSR). In SSR, when checkpointing mechanism checkpointing a program, a copy of the current file system states are also saved in stable storage. When checkpointing mechanism roll backing the program after a failure, the file system states are replaced by the copy. DSR dynamically follows the tracks of a program's running, and logs every such file operation that modifies the file system states and the necessary information that can undo these operations in stable storage. When checkpointing mechanism roll backing the program, DSR revert the file system states to the last checkpoint by undoing all the file operations used by the program.

In general, it is unpredictable how a program will change the file system states during its running. Hence, SSR should save the states of all the file system that are permitted the program to access. Then a lot of unnecessary information is saved, so SSR is much inefficient. Moreover, the high disk space overhead makes SSR difficult to implement. On the contrary, DSR dynamically keeps the tracks of a program's real running, only the useful information is saved. So, DSR is much more efficient and practical than SSR. SCR algorithm is just based on DSR strategy.

In Unix, a file system is composed of files and directories. Applications access file systems by using system calls provided by OS. In SCR, system calls related to file access are classified into idempotent operations and non-idempotent operations. SCR defines a save operation and an undo operation for each non-idempotent operation. A set of stacks, called **undo stacks** in SCR, that work on stable storage (such as disks) are used to save information that can undo the file system changes by a distributed program's running.

### **Definition 1** A file system's states

A file system's **states** are its directories' and files' name, contents, location, owner, mode, and link number etc. These characters do not rely on any program's running. SCR is responsible for saving and restoring such features of a file system. (Note: A file system's states do not include a file's open mode, open file handle, read and write pointer's offset etc. Because these states can not exist independent of a program's running, these states should be a part of a program's running states. So, they should be saved/restored by the checkpointing mechanism.)

### **Definition 2** Idempotent operations and Non-idempotent operations

All system calls about file accesses are classified into **idempotent** operations and **non-idempotent** operations. **Non-idempotent** operations are all the system calls that may modify a file system's states. **Idempotent** operations are all the systems on file systems that never change a file system's states. For examples, in SunOS 4.1.3, `create()`, `mkdir()`, `remove()`, `rmdir()`, `rename()`, `write()`, `chown()`, `chmod()`, `link()`, and `unlink()` etc are non-idempotent operations; `read()`, `access()`, `fstat()`, `stat()` etc are idempotent operations. In a broad sense, all idempotent operations are some kind of read operations, and all non-idempotent operations are some kind of write operations.

### **Definition 3** NOP

Suppose  $nop_i$  ( $i=1, \dots, n$ ) is an non-idempotent operation,  $op_j$  ( $j=1, \dots, m$ ) is an idempotent operation. **NOP** is such a set of file operations that  $\forall nop_i$  ( $i=1, \dots, n$ )  $\in$  **NOP**, and  $\forall op_j$  ( $j=1, \dots, m$ )  $\notin$  **NOP**.

#### **Definition 4 Undo Stack**

An **undo stack**, composed of a set of **local undo stacks**, works on stable storage such as disks. The data unit of undo stacks is called **undo structure** in SCR. An undo structure logs a non-idempotent operation's name, and the necessary information that can undo the non-idempotent operation. In SCR, every machine holds a local undo stack for a distributed program. When the program executes a non-idempotent operation to a machine's file system, the machine's local undo stack for the program will be pushed into an undo structure at the same time.

#### **Definition 5 Save operations and Undo operations**

A **save operation** ( $sop_i$ ) and an **undo operation** ( $uop_i$ ) are defined for each  $nop_i$ .  $Sop_i$ s and  $uop_i$ s are all atomic operations. A  $sop_i$  creates and fills the undo structure for the correspondent  $nop_i$  and pushes it into the correspondent local undo stack, then finishes the file access of the  $nop_i$ . An  $uop_i$  undoes the  $nop_i$  according to the  $nop_i$ 's undo structure, then pop up the undo structure from the correspondent local undo stack.

### **3 SCR (Save, Clean, Restore) Algorithm**

A distributed program is composed of a set of concurrent processes running on different machines. Consistent schedule is used to coordinate the concurrent file operations of a program. Each machine runs a manage process (MP) to manage the local file systems.

#### **Algorithm Description**

Every MP holds a local undo stack for a program, which is NULL at the beginning.

During normal running, when a process of a program is to execute a  $nop_i$  to a machine's file system, the process sends a requirement to the machine's MP, and waits for the result. When a process of a program is to execute an  $op_i$ , the process operates the file access directly.

At normal time, MPs wait for  $nop_i$  requirements in loops. MPs execute the correspondent  $sop_i$  and return the result for each  $nop_i$  requirement in FIFO order. When executed, a  $sop_i$  will push the undo structure for the  $nop_i$  into the local undo stack.

When a distributed program taking global checkpoints, every MP cleans its local undo stack of the program.

When a distributed program roll-backed, each MP do  $uop_i$ s in loops, until all the undo structures are popped up from the local undo stack.

At the end of the program running, MPs clean up all undo stacks of the program.

#### **Proof of Correctness**

Suppose a distributed program is composed of  $q$  concurrent processes running on  $p$  machines ( $q \geq p$ ), and at the  $i$ th checkpoint time the file system states are  $S_i$ .  $S_i = \{S1_i, S2_i, \dots, SP_i\}$ ,  $Sk_i$  ( $k=1, \dots, P$ ) are the machine  $k$ 's local file system states.  $S_0$  are the file system states at the beginning of the program running. According to SCR algorithm, at the  $i$ th checkpoint time all the local undo stacks of the program are null and after the  $i$ th checkpoint:

1. During normal running, when a process of the program executes a  $nop_i$ , the  $nop_i$ 's undo structure will be pushed into the very machine's local undo stack. In another words, when a machine's file system's states are to be changed, the necessary information that can undo the changes will be saved into the machine's local undo stack at first.
2. When a failure occurs, suppose the global file system states are  $S_m = \{S1_m, \dots, SP_m\}$ . Without losing generality, we also suppose at this time the machine  $k$ 's ( $k=1, \dots, P$ ) local undo stack are  $\{ud\_info[1], \dots, ud\_info[mk-1], ud\_info[mk]\}$ . From 1, we know the program has executed  $mk$  nops ( $nop_{i_1}, \dots, nop_{i_{mk}}$ ) since the last checkpoint time (the  $i$ th checkpoint). Because idempotent operations never vary a file system states, and all file operations in SCR are atomic operations, so the

vary procedure of machine k's file system must be  $Sk_{i_0} \rightarrow Sk_{i_1} \rightarrow \dots \rightarrow Sk_{i_{mk}}$  (note:  $Sk_{i_0}$  is  $Sk_i$ , and  $Sk_{i_{mk}}$  is  $Sk_{mk}$ ).  $Sk_{i_{(j-1)}} \rightarrow Sk_{i_j}$  ( $j=1, \dots, mk$ ) is caused by  $rop_{i_j}$  ( $j=1, \dots, mk$ ).

3. When the program roll-backed, machine k's MP will executes mk rops:  $rop_{i_{mk}}, \dots, rop_{i_1}$ . And machine k's file system states will take the following changes,  $Sk_{i_{mk}} \rightarrow, \dots, \rightarrow Sk_{i_1} \rightarrow Sk_i$ . So the global file system states are reverted to  $Si$ , which are just the file system states at the last checkpoint time. At the same time all undo stacks of the program are cleaned up.
4. When it is time to take a new checkpoint, the global file system states are  $S_{i+1}$ . At this time all undo stacks of the program are cleaned, then when the next failure occurs, the global file system states will be reverted to  $S_{i+1}$  by SCR.
5. At the end of the program running, no information need saving. So, SCR clears all of the program's undo stacks.

Above all, SCR algorithm can revert the file system states related to a program to the last checkpoint time when the program is roll-backed. By using SCR algorithm, user applications can use any file operation in a fault-tolerance system using synchronous checkpointing algorithms.

#### 4 An implementation example of SCR

In the section, we present an implementation of SCR algorithm, which is realized on DPVM<sup>[17,18]</sup>. DPVM is an enhanced PVM on SunOS 4.1.3, which realized process migration and fault-tolerance by using synchronous checkpointing algorithm.

##### 1 Define undo stack

All local undo stacks work on disks.

###### (1) Undo Structure

```
Structure undo_info{
    int opflag;      /*      opflag = 1: write()      operation;
                      2: delete()    operation;
                      3: rename()    operation;
                      ...
    */
    char init_fn[256]; /* file name string */
    char effect_fn[256]; /* file name string */
    char temp_fn[256]; /* file name string */
}
```

###### (2) PUSH operation

Push an undo\_info structure on the top of the local undo stack.

###### (3) POP operation

Pop the top undo\_info structure from the local undo stack. If the undo\_info structure's temp\_fn item is not null, delete the file whose name is temp\_fn.

2. System calls of SunOS4.1.4 about file operations are divided into idempotent operations and non-idempotent operations. In the section, we only use write(), delete() and rename() system calls as non-idempotent operation examples.

##### 2.1 Define NOP

NOP= {write(), delete(), rename()}.

##### 2.2 Define the save and undo operation for write() system calls

###### (1) save operation – sop1

A file is divided into pages of the same size, and every page has a flag to point out whether the page has been changed from the last checkpoint. Sop1 first determine whether all of the pages are to be written have marked with `changed_flag`. (a) If there are some pages without being set with `changed_flag`, sop1 creates a new `undo_info` structure and a new temp file. Sop1 saves such pages of the file into the temp file, and set these pages with `changed_flag` at the same time. Then sop1 set the `undo_info` structure's `opflag` with 1, `init_fn` with the name of the file is to be written into, `temp_fn` with the name of the temp file. After that, sop1 executes PUSH operation and `write()` operation. (b) If no such pages, sop1 simply executes `write()` operation.

**(2) undo operation – uop1**

Uop1 writes the pages saved in the temp file whose name is `temp_fn` back to the file whose name is `init_fn`, clear these pages' `changed_flag`, and executes the POP operation.

**2.3 Define the save and undo operation for delete() system calls**

**(1) save operation – sop2**

Sop2 creates a new `undo_info` structure and generates a temp file name. Then sop2 set the `undo_info` structure's `opflag` with 2, `init_fn` with the name of the file is to be deleted, `temp_fn` with the new generated temp file name. After that, sop2 executes the rename operation: rename `init_fn` `temp_fn`, and executes the PUSH operation.

**(2) undo operation – uop2**

Uop2 executes the rename operation: rename `temp_fn` `init_fn`, and the POP operation.

**2.4 Define the save and undo operation for rename() system call**

**(1) save operation – sop3**

Sop3 creates a new `undo_info` structure, and set the structure's `opflag` with 3, `init_fn` with old name of the file, `effect_fn` with the new name of the file. Then sop3 executes `rename()` operation and PUSH operation.

**(2) undo operation – uop3**

Uop3 executes the rename operation: rename `effect_fn` `init_fn`, and the POP operation.

**3. Add a wrap to each system call(`f_syscall()`) on file systems:**

```
if (f_syscall() ∈ NOP) then{
    send the f_syscall() requirment to the correspondent MP;
    wait for the result;
}else{
    call f_syscall();
}
```

**4. Design the working flow of process MP**

**(1) During the normal running time**

```
While(1){
    Wait for f_syscall() requirments;
    Execute the save operation for f_syscall();
    Return the results to the process who sent the f_syscall() requirment;
}
```

**(2) At the time of a program is roll-backed**

```
While (the local undo stack is not NULL){
    Execute the undo operation according to the top undo_info structure of the local undo stack;
}
clear the changed_flag of every page of all changed local files;
```

### (3) At a new checkpoint time or at the end of a program running

While (the local undo stack is not NULL){

Executes the POP operation according to the top undo\_info structure of the local undo stack;

}

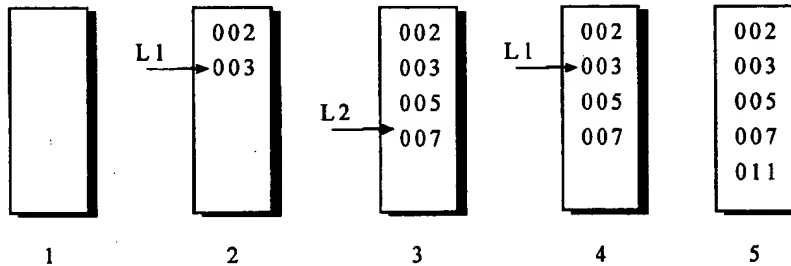
clear the changed\_flag of every page of all changed local files;

### 5 Discussions on performance

SCR algorithm's overheads lie in two aspects. One is caused by consistent schedule, the other is caused by logging and clearing undo structures dynamically. To reduce the overheads of the first respect relies on improving the schedule policy, and it is our further work. And the following discusses two strategies to reducing the overheads of the second respect.

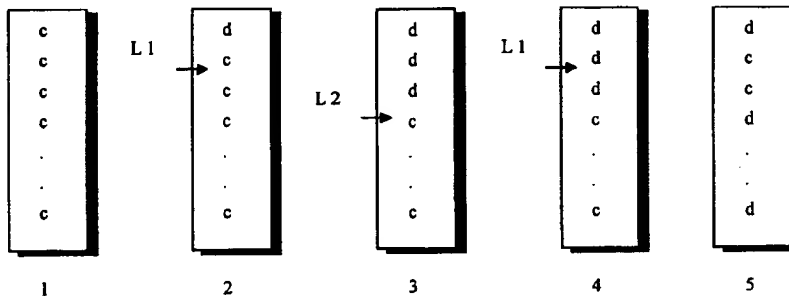
1.Reducing the information logged in undo structures for each non-idempotent operation. For example, a file is 1M bytes and an application will read and write the file during its running. To reducing the information logged in the undo structure for write() system call, the file is divided into pages like sop1( section 4). If the page size is 50k bytes and a write() system call writes 50K bytes into the file, then the write()'s undo structure need logging 100K bytes(2 pages) at most not 1M bytes.

2.Reducing the undo structures need logging in undo stacks. For example, if you have some knowledge about an application's activities, you can exclude some non-idempotent operations from NOP aggregate.



**Figure 1 write-only operations**

Figure 1 is a program that generates prime numbers. The program writes 002, 003, ..., into the output file during its running. Because the program only executes write operations on the file, so we can exclude write() system call from NOP. Then during the program's fault-tolerance running, nothing will be logged in its undo stacks. However, this doesn't effect the fault-tolerance function. Refer to figure 1, at the begin of the program's running, the output file is NULL (figure1(1)). At the checkpoint time, the output file write pointer's offset is L1 (figure1(2)). And when a failure occurs, the file write pointer's offset is L2 (figure1(3)). When the program is roll-backed, the write pointer's offset is set to L1, which is the value at the last checkpoint time. However, because nothing is logged in the program's undo stacks, so the output file doesn't revert to the last checkpoint time (figure1(4)). Because the program only executes write() operation to the file, the program still can finish correctly (figure1(5)).



**Figure 2 read and write operations**

However, for some application NOP must include write() system call, otherwise the program's running is unpredictable. Refer to figure 2, a file's contents are a list of char 'c'(figure2(1)); the program executes the following operations on the file: change all char 'c' to 'd', change all char 'd' to 'c'. At the checkpoint time, the file write pointer's offset is L1(figure2(2)). And when a failure occurs, the pointer's offset is L2(figure2(3)). As the program is roll-backed, the write pointer is set to L1. If NOP does not include write() system call, the file's contents will not be reverted to the last checkpoint time(figure2(4)). Then, at the end of the program's running the file content will be figure 2(5). Clearly, it is not the expected result, which should be a list of char 'd'. The above two examples show when NOP must include write() system call and when needn't. In Condor system etc, users are allowed to use read-only or write-only operations to files, but random write and read operations are inhibited. The reason is also similar with the above description.

## 6 Conclusion

File systems are very important environments for programs. During running, a program needs access file systems for reading input and writing output from time to time. Existing fault-tolerance systems only rollback a program's running states and dose not restore the file system states correspondingly. For this reason, Condor, Mist and other fault-tolerance systems disallow their users access file systems arbitrarily except read-only or write-only operations. SCR algorithm, based on atomic operation and consistent schedule, can resolve this problem. By using SCR algorithm, users are allowed to use any file operation in their programs. But SCR algorithm only supports synchronous checkpointing algorithms now, how to support asynchronous checkpointing algorithms is our next work in the future.

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